

Ordinary Differential Equations - Part 21

System of linear differential equations:

$$\dot{x} = A(t)x + b(t) \quad (*)$$

with
interval in \mathbb{R} $\xrightarrow{\text{continuous}}$ $A(t) \in \mathbb{R}^{n \times n}$
 $I \ni t \xrightarrow{\text{continuous}}$ $b(t) \in \mathbb{R}^n$

We already know:

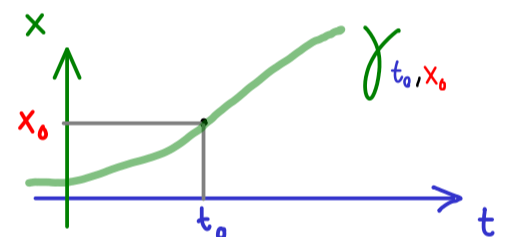
- the homogeneous part of $(*)$ ($\dot{x} = A(t)x$)

has an n -dimensional solution space S_0

- the initial value problem (IVP) $\begin{matrix} t_0 \\ x_0 \end{matrix}$ has a global solution

$$\begin{cases} \dot{x} = A(t)x + b(t) \\ x(t_0) = x_0 \end{cases}$$

$$\gamma_{t_0, x_0} : I \rightarrow \mathbb{R}^n$$



Solution set:

$$S := \left\{ \beta : I \rightarrow \mathbb{R}^n \text{ continuously differentiable} \mid \beta \text{ solution of } (*) \right\}$$

$$S_0 + \gamma_{t_0, x_0} := \left\{ \alpha + \gamma_{t_0, x_0} \mid \alpha \in S_0 \right\} \quad (\text{affine subspace})$$

Show $S = S_0 + \gamma_{t_0, x_0}$: (\supseteq) Take $\alpha \in S_0$: $A(t)(\alpha(t) + \gamma_{t_0, x_0}(t)) + b(t)$

$$= \underbrace{A(t)\alpha(t)} + \underbrace{A(t)\gamma_{t_0, x_0}(t) + b(t)}$$

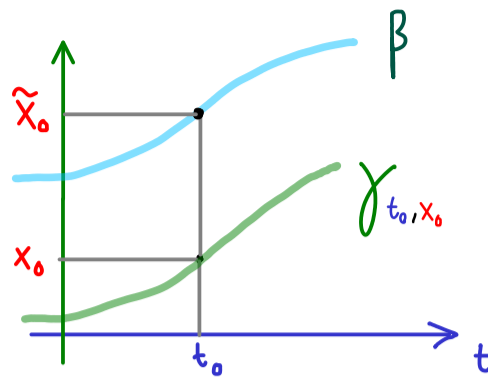
$$= \dot{\alpha}(t) + \dot{\gamma}_{t_0, x_0}(t)$$

$$= (\alpha + \gamma_{t_0, x_0})'(t)$$

$$\Rightarrow \alpha + \gamma_{t_0, x_0} \in S$$

(\subseteq) Take $\beta \in \mathcal{S}$ and set $\tilde{x}_0 := \beta(t_0)$

$\Rightarrow \beta$ is solution of $(\text{IVP}_{\tilde{x}_0}^{t_0})$



Choose $\alpha \in \mathcal{S}_0$ as the solution

of the initial value problem

$$\begin{cases} \dot{x} = A(t)x \\ x(t_0) = \tilde{x}_0 - x_0 \end{cases}$$

Then: $\alpha + \gamma_{t_0, x_0} \in \mathcal{S}$ with $(\alpha + \gamma_{t_0, x_0})(t_0) = \alpha(t_0) + \gamma_{t_0, x_0}(t_0)$
 $= \tilde{x}_0 - x_0 + x_0 = \tilde{x}_0$

$\Rightarrow \alpha + \gamma_{t_0, x_0}$ is solution of $(\text{IVP}_{\tilde{x}_0}^{t_0})$

uniqueness

$\Rightarrow \beta = \alpha + \gamma_{t_0, x_0}$

□

Result: The solution set of $\dot{x} = A(t)x + b(t)$ is given by

$$\mathcal{S} = \mathcal{S}_0 + \gamma$$

where \mathcal{S}_0 is the solution space of the homogeneous part $\dot{x} = A(t)x$

and γ is a particular solution of $\dot{x} = A(t)x + b(t)$.

(\mathcal{S} is an n-dimensional affine subspace)