

 $\dot{X} = V(X)$

 $X(0) = X_0$

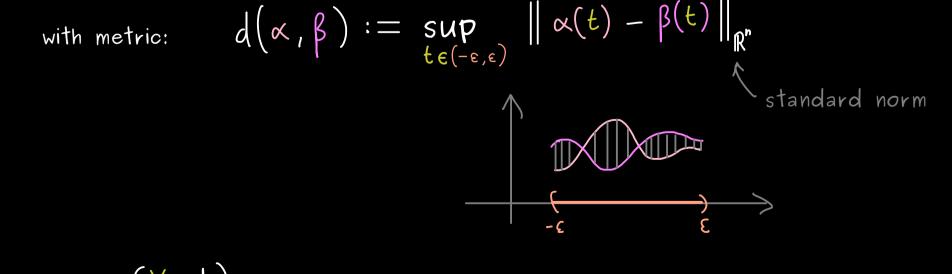
(fixed point equation)

 $\boldsymbol{\alpha}\,:\,\mathbb{R}\longrightarrow\mathbb{R}^n$ is a solution of

 $\langle \Longrightarrow \Phi(\alpha) = \alpha$

Ordinary Differential Equations - Part 12

$$\frac{\text{For (1):}}{\chi} = \left\{ \begin{array}{l} \chi : (-\varepsilon, \varepsilon) \longrightarrow \widetilde{\mathcal{U}} \subseteq \mathbb{R}^{n} \text{ in the domain of } \\ \text{with property (k)} \\ \text{(see below)} \end{array} \right| \left\{ \begin{array}{l} \chi \text{ continuous }, \\ \chi(0) = \chi_{0} \end{array} \right\}$$



Now we know:

Fact:
$$(X, d)$$
 is a complete metric space.

$$\frac{\Phi(\alpha)(t)}{\Phi(\alpha)(t)} = x_{o} + \int_{0}^{t} v(\alpha(s)) ds \quad \text{gives a map} \quad \Phi: X \longrightarrow X$$

$$d(\Phi(\alpha), \Phi(\beta)) = \sup_{t \in (-e,e)} \| \Phi(\alpha)(t) - \Phi(\beta)(t) \|_{\mathbf{R}^{n}}$$

$$= \sup_{t \in (-e,e)} \| \int_{0}^{t} (v(\alpha(s)) - v(\beta(s))) ds \|_{\mathbf{R}^{n}}$$

$$\text{triangle inequality}$$

$$for integrals \quad \leq \sup_{t \in (-e,e)} \int_{0}^{t} \| v(\alpha(s)) - v(\beta(s)) \|_{\mathbf{R}^{n}} ds \quad (ength (interval) + interval))$$

$$\leq \sup_{t \in (-e,e)} \left\| ength([0,t]) \cdot \sup_{s \in [0,t]} \| v(\alpha(s)) - v(\beta(s)) \|_{\mathbf{R}^{n}}$$

$$\leq \varepsilon \cdot \sup_{s \in (-e,e)} \| v(\alpha(s)) - v(\beta(s)) \|_{\mathbf{R}^{n}}$$

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(e) needed
$$\leq c \cdot L + d(\alpha, \beta) \quad contraction$$

$$\leq 1 \quad \text{for } \varepsilon \text{ small enough}$$

Picard-Lindelöf theorem

For

$$P^{h}$$
 is a linearity south and P^{h}

 $V: U \longrightarrow |K|$ loc. Lipschitz continuous, $X_0 \in U$.

Then there is $\varepsilon > 0$ and a unique solution $\alpha : (-\varepsilon, \varepsilon) \longrightarrow U$

for the initial value problem

$$\dot{X} = V(X)$$

 $X(0) = X_0$

Definition of $\widetilde{\mathcal{U}}$ with property (*)

V being locally Lipschitz continuous at X_0 means:

So we need $\alpha(s), \beta(s) \in B_{s}(x)$ for all $s \in (-\varepsilon, \varepsilon)$. Hence: $\widetilde{\mathcal{N}} := B_{s}(x)$ (not a problem for the solution since we choose ε as small as we want)