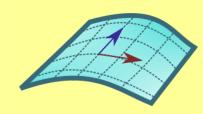
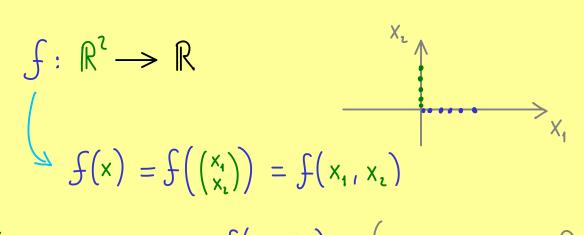
ON STEADY

## The Bright Side of Mathematics





## Multivariable Calculus - Part 4



If we fix  $\widetilde{X}_2$ , then  $X_1 \longmapsto \int (X_1, \widetilde{X}_2)$  (ordinary function  $\mathbb{R} \to \mathbb{R}$ )

For  $f: \mathbb{R}^n \longrightarrow \mathbb{R}$ , we define partial derivatives: Definition:

Notations:

f is called partially differentiable with respect to  $X_1$  at  $\widetilde{X} = \begin{pmatrix} X_1 \\ \vdots \\ X_n \end{pmatrix} \in \mathbb{R}^n$ 

if 
$$\underbrace{\int_{h\to 0}^{lim} \frac{\int (\widetilde{x}_1 + h, \widetilde{x}_2, ..., \widetilde{x}_n) - \int (\widetilde{x}_1, \widetilde{x}_2, ..., \widetilde{x}_n)}{h}}_{\text{exists}}$$
 exists

 $\frac{\partial f}{\partial x}(\tilde{x}) = \text{partial derivative of } f \text{ w.r.t. } x_1 \text{ at } \tilde{x}$ 

$$= (\mathfrak{I}^{\mathsf{x'}} \mathfrak{t})(\mathfrak{x}) = (\mathfrak{D}^{\mathsf{x'}} \mathfrak{t})(\mathfrak{x}) = \mathfrak{t}^{\mathsf{x'}}(\mathfrak{x})$$

Similar definition for the other components:

$$\frac{\partial f}{\partial x_{i}}(\widetilde{x}) = \lim_{h \to 0} \frac{f(\widetilde{x}_{i}, \widetilde{x}_{i} + h, \widetilde{x}_{j}, \dots, \widetilde{x}_{h}) - f(\widetilde{x}_{i}, \widetilde{x}_{i}, \dots, \widetilde{x}_{h})}{h}$$

 $f: \mathbb{R}^3 \longrightarrow \mathbb{R}$ ,  $f(x_1, x_2, x_3) = x_1^2 \cdot x_2 \cdot \sin(x_3) + x_3$ Examples:

$$\frac{\partial f}{\partial x_1}(\widetilde{x}_1,\widetilde{x}_2,\widetilde{x}_3) = 2 \cdot \widetilde{x}_1 \cdot \widetilde{x}_2 \cdot \sin(\widetilde{x}_3) \qquad \text{partially differentiable w.r.t. } x_1 \\ \text{for all } \widetilde{x} \in \mathbb{R}^3.$$

$$\Rightarrow \mathbb{R}$$
new function: 
$$\frac{\partial f}{\partial x_1}: \mathbb{R}^3 \longrightarrow \mathbb{R}$$

$$\frac{\partial x_1}{\partial f}(\widetilde{x}_1,\widetilde{x}_1,\widetilde{x}_3) = \widetilde{x}_1^{i} \cdot sin(\widetilde{x}_3) , \qquad \frac{\partial x_3}{\partial f}(\widetilde{x}_1,\widetilde{x}_1,\widetilde{x}_3) = \widetilde{x}_1^{i} \cdot \widetilde{x}_1 \cdot cos(\widetilde{x}_3) + 1$$