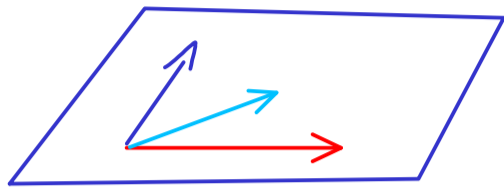




## Linear Algebra - Part 24

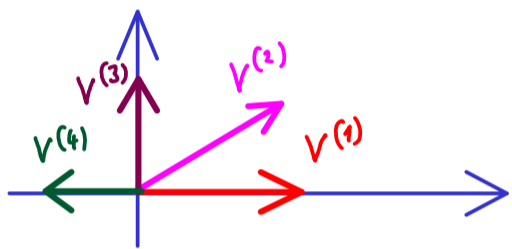
subspace:



$U \subseteq \mathbb{R}^n$  with

- (a)  $0 \in U$
- (b)  $u \in U, \lambda \in \mathbb{R} \Rightarrow \lambda \cdot u \in U$
- (c)  $u, v \in U \Rightarrow u + v \in U$

plane:  $\mathbb{R}^2$



$$\text{Span}(v^{(1)}, v^{(2)}, v^{(3)}, v^{(4)}) = \mathbb{R}^2$$

$$\text{Span}(v^{(1)}, v^{(3)}) = \mathbb{R}^2$$

$$\text{Span}(v^{(1)}, v^{(4)}) = \mathbb{R} \times \{0\} \neq \mathbb{R}^2$$

Definition:  $U \subseteq \mathbb{R}^n$  subspace,  $\mathcal{B} = (v^{(1)}, v^{(2)}, \dots, v^{(k)})$ ,  $v^{(j)} \in \mathbb{R}^n$ .

$\mathcal{B}$  is called a basis of  $U$  if:

(a)  $U = \text{Span}(\mathcal{B})$

(b)  $\mathcal{B}$  is linearly independent

Example:

$$\mathbb{R}^n = \text{Span}(e_1, \dots, e_n)$$

standard basis of  $\mathbb{R}^n$

$$\mathbb{R}^3 = \text{Span}\left(\begin{pmatrix} -3 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 2 \\ 0 \\ -1 \end{pmatrix}\right)$$

basis of  $\mathbb{R}^3$