

## Linear Algebra - Part 24





$$\frac{\text{plane:}}{\Lambda} \qquad \text{Span}\left(V^{(1)}, V^{(1)}, V^{(3)}, V^{(4)}\right) = \mathbb{R}^{2}$$



$$Span(v^{(1)}, v^{(3)}) = \mathbb{R}^{2}$$

Span(
$$v^{(i)}, v^{(i)}$$
) =  $\mathbb{R} \times \{0\} \neq \mathbb{R}^2$ 

$$U \subseteq \mathbb{R}'$$

Definition: 
$$\mathbb{N} \subseteq \mathbb{R}^n$$
 subspace,  $\mathbb{B} = (V^{(1)}, V^{(1)}, \dots, V^{(k)})$ ,  $V^{(j)} \in \mathbb{R}^n$ .

 $\mathfrak{F}$  is called a basis of  $\mathfrak{h}$  if:

(a) 
$$U = Span(B)$$

(b) B is linearly independent

Example:

$$\mathbb{R}^n = \operatorname{Span}(e_1, \dots, e_n)$$

standard basis of  $\mathbb{R}^{^{\mathsf{h}}}$ 

$$\mathbb{R}^{3} = \operatorname{Span}\left(\begin{pmatrix} -3 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 2 \\ 0 \\ -1 \end{pmatrix}\right)$$
basis of  $\mathbb{R}^{3}$