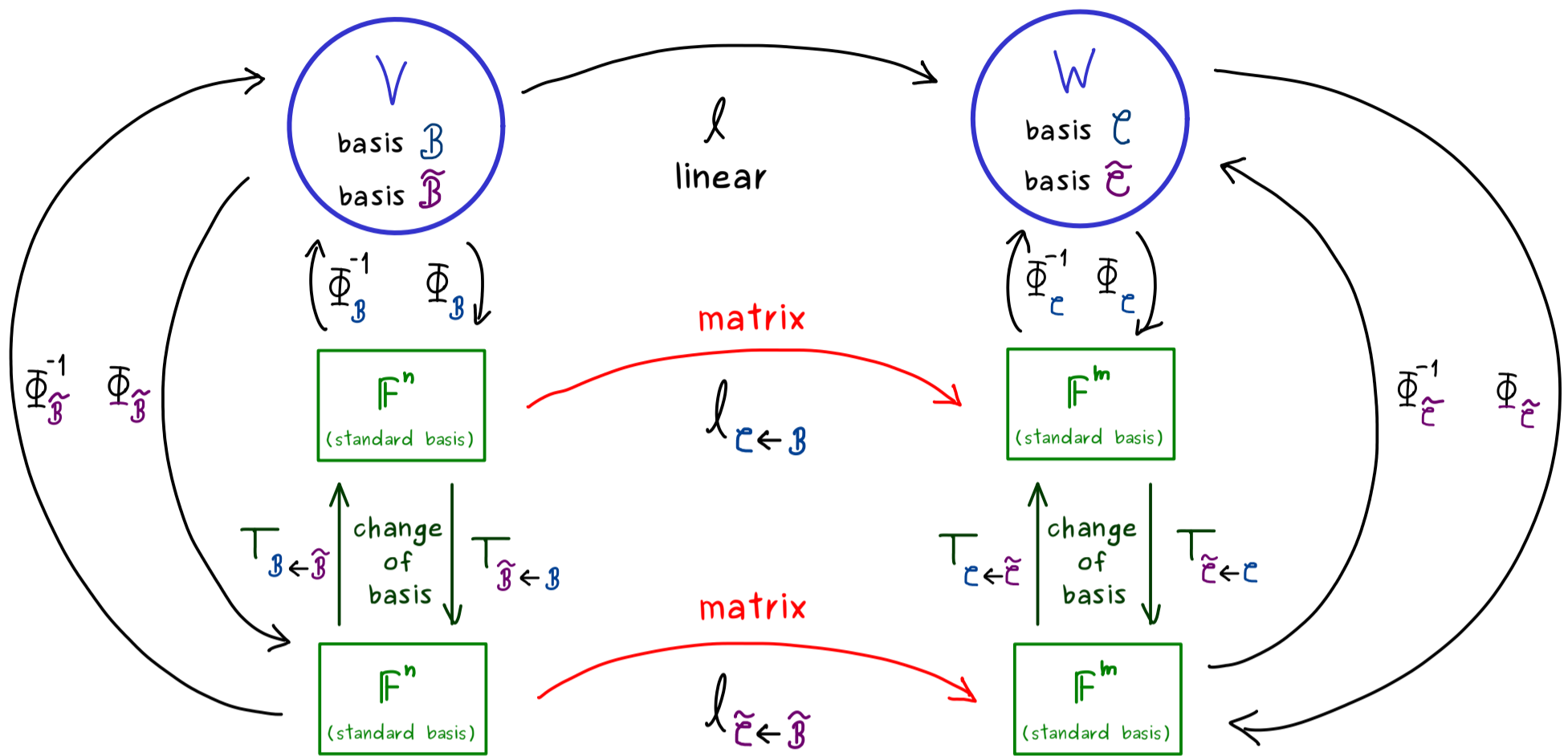


# Abstract Linear Algebra - Part 27



Result:

$$l_{\tilde{\mathcal{C}} \leftarrow \tilde{\mathcal{B}}} = T_{\tilde{\mathcal{C}} \leftarrow \mathcal{C}} l_{\mathcal{C} \leftarrow \mathcal{B}} T_{\mathcal{B} \leftarrow \tilde{\mathcal{B}}}$$

Example:  $l: \mathcal{P}_3(\mathbb{R}) \rightarrow \mathcal{P}_2(\mathbb{R})$ ,  $l(p) = p'$  linear map!

$$\mathcal{B} = (m_3, m_2, m_1, m_0) \quad \mathcal{C} = (m_2, m_1, m_0)$$

$$\tilde{\mathcal{B}} = (2m_3 - m_1, m_2 + m_0, m_1 + m_0, m_1 - m_0), \quad \tilde{\mathcal{C}} = (m_2 - \frac{1}{2}m_1, m_2 + \frac{1}{2}m_1, m_0)$$

matrix representation:  $l_{\mathcal{C} \leftarrow \mathcal{B}} = \begin{pmatrix} 3 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{pmatrix}$

change-of-basis matrices:  $T_{\mathcal{B} \leftarrow \tilde{\mathcal{B}}} = \begin{pmatrix} 2 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ -1 & 0 & 1 & 1 \\ 0 & 1 & 1 & -1 \end{pmatrix}$

$$T_{\mathcal{E} \leftarrow \tilde{\mathcal{E}}} = \begin{pmatrix} 1 & 1 & 0 \\ -\frac{1}{2} & \frac{1}{2} & 0 \\ 0 & 0 & 1 \end{pmatrix} \xrightarrow{\text{inverse}} T_{\tilde{\mathcal{E}} \leftarrow \mathcal{E}} = \begin{pmatrix} \frac{1}{2} & -1 & 0 \\ \frac{1}{2} & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\begin{aligned} l_{\tilde{\mathcal{E}} \leftarrow \hat{\mathcal{B}}} &= T_{\tilde{\mathcal{E}} \leftarrow \mathcal{E}} l_{\mathcal{E} \leftarrow \mathcal{B}} T_{\mathcal{B} \leftarrow \hat{\mathcal{B}}} = \begin{pmatrix} \frac{1}{2} & -1 & 0 \\ \frac{1}{2} & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 3 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 2 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ -1 & 0 & 1 & 1 \\ 0 & 1 & 1 & -1 \end{pmatrix} \\ &= \begin{pmatrix} \frac{1}{2} & -1 & 0 \\ \frac{1}{2} & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 6 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ -1 & 0 & 1 & 1 \end{pmatrix} = \begin{pmatrix} 3 & -2 & 0 & 0 \\ 3 & 2 & 0 & 0 \\ -1 & 0 & 1 & 1 \end{pmatrix} \end{aligned}$$