



Abstract Linear Algebra - Part 9

$$T_{\mathcal{B} \leftarrow \mathcal{C}} \begin{pmatrix} \vdots \\ \vdots \end{pmatrix}_{\mathcal{C}} = \begin{pmatrix} \vdots \\ \vdots \end{pmatrix}_{\mathcal{B}}$$

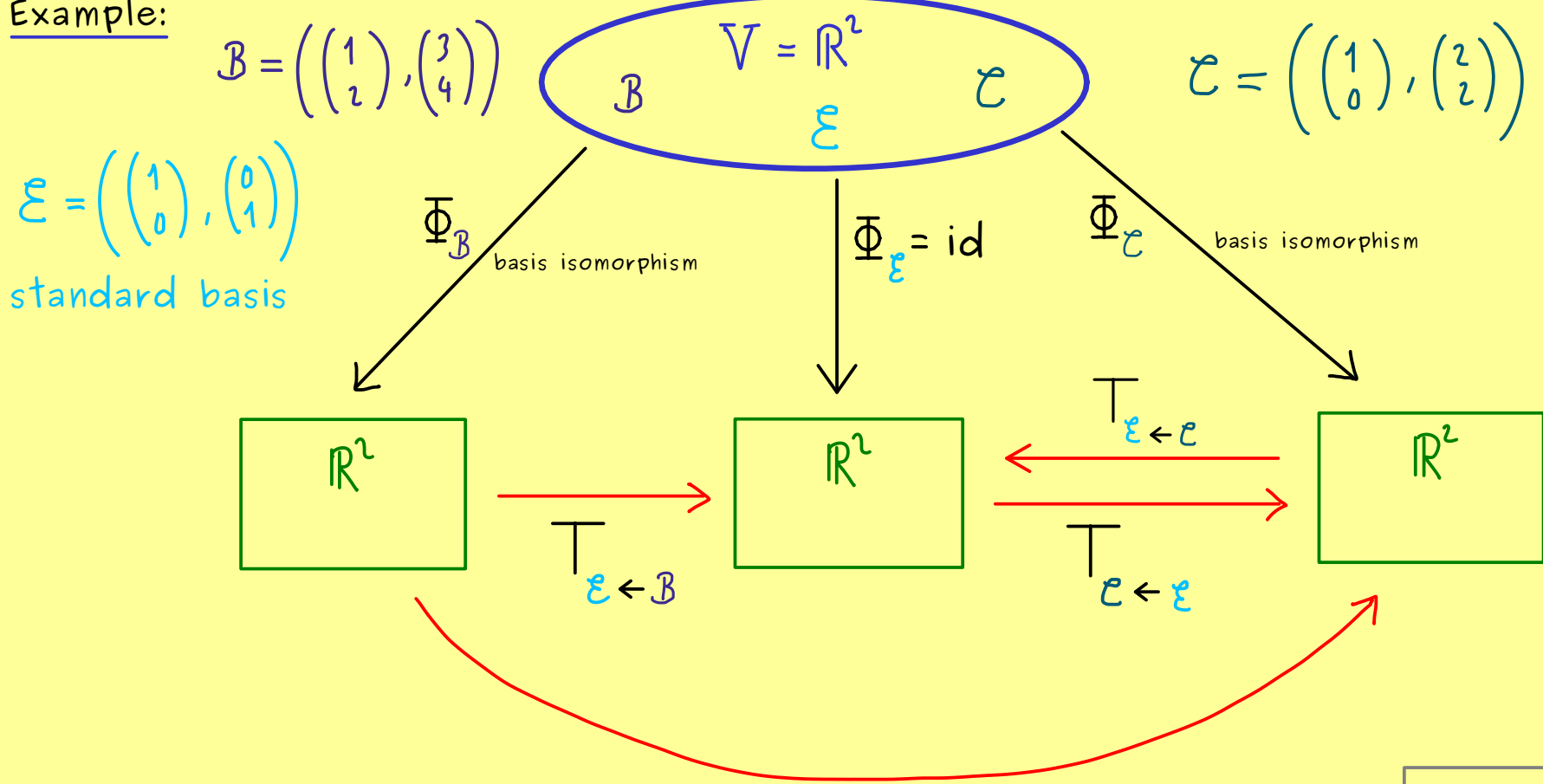
change-of-basis matrix

$\Phi_{\mathcal{C}}(v)$ $\Phi_{\mathcal{B}}(v)$

V vector space of dimension n

$T_{\mathcal{B} \leftarrow \mathcal{C}}$ $(n \times n)$ -matrix invertible

Example:



We already know:

$$T_{\mathcal{E} \leftarrow \mathcal{B}} = \begin{pmatrix} \Phi_{\mathcal{E}}(b_1) & \Phi_{\mathcal{E}}(b_2) \end{pmatrix} = \begin{pmatrix} | & | \\ b_1 & b_2 \\ | & | \end{pmatrix} = \begin{pmatrix} 1 & 3 \\ 2 & 4 \end{pmatrix}$$

$$T_{\mathcal{E} \leftarrow \mathcal{C}} = \begin{pmatrix} \Phi_{\mathcal{E}}(c_1) & \Phi_{\mathcal{E}}(c_2) \end{pmatrix} = \begin{pmatrix} | & | \\ c_1 & c_2 \\ | & | \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ 0 & 2 \end{pmatrix}$$

We can calculate:

$$T_{\mathcal{C} \leftarrow \mathcal{B}} = T_{\mathcal{C} \leftarrow \mathcal{E}} T_{\mathcal{E} \leftarrow \mathcal{B}}$$

$$= \underbrace{\left(T_{\mathcal{E} \leftarrow \mathcal{C}} \right)^{-1}}_X T_{\mathcal{E} \leftarrow \mathcal{B}}$$

calculate product immediately!

$$\underbrace{T_{\mathcal{E} \leftarrow \mathcal{C}}}_X = T_{\mathcal{E} \leftarrow \mathcal{B}}$$

$$\begin{pmatrix} 1 & 2 \\ 0 & 2 \end{pmatrix} = \begin{pmatrix} 1 & 3 \\ 2 & 4 \end{pmatrix}$$

$$\Rightarrow \text{solve } \left(\begin{array}{cc|cc} 1 & 2 & 1 & 3 \\ 0 & 2 & 2 & 4 \end{array} \right) \xrightarrow{\text{I} \cdot \frac{1}{2}} \left(\begin{array}{cc|cc} 1 & 2 & 1 & 3 \\ 0 & 1 & 1 & 2 \end{array} \right)$$

$$\xrightarrow{\text{I} - 2\text{II}} \left(\begin{array}{cc|cc} 1 & 0 & -1 & -1 \\ 0 & 1 & 1 & 2 \end{array} \right)$$

$$X = T_{\mathcal{C} \leftarrow \mathcal{B}} = \begin{pmatrix} -1 & -1 \\ 1 & 2 \end{pmatrix}$$