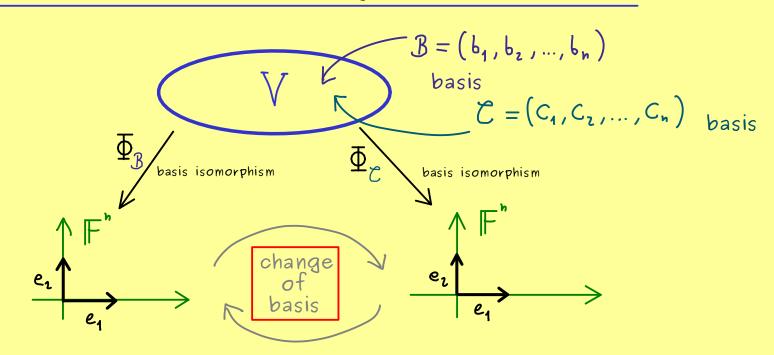
ON STEADY

## The Bright Side of Mathematics



## Abstract Linear Algebra - Part 7



Recall: 
$$\Phi_{\mathfrak{B}}: V \longrightarrow \mathbb{F}^{n}$$
 given by  $\Phi_{\mathfrak{B}}(b_{j}) = e_{j}$  for all  $j$ 

$$\Phi_{\mathfrak{B}}^{-1}: \mathbb{F}^{n} \longrightarrow V \text{ given by } \Phi_{\mathfrak{B}}^{-1}(e_{j}) = b_{j} \text{ for all } j$$
For each  $v \in V: V = \Phi_{\mathfrak{B}}^{-1}\left(\begin{pmatrix} \text{coordinate} \\ \text{vector} \end{pmatrix}\right)$ 

Example: 
$$P_{\mathbf{z}}(\mathbb{R})$$
 with basis  $\mathcal{B} = (\mathbf{m_0}, \mathbf{m_1}, \mathbf{m_2})$  where  $\mathbf{m_0}(\mathbf{x}) = 1$ ,  $\mathbf{m_1}(\mathbf{x}) = \mathbf{x}$ ,  $\mathbf{m_2}(\mathbf{x}) = \mathbf{x}^2$ 

For  $\mathbf{p} \in P_{\mathbf{z}}(\mathbb{R})$  given  $\mathbf{p}(\mathbf{x}) = 3\mathbf{x}^2 + 8\mathbf{x} - 2$ 

$$\rho = (-2) \cdot \mathbf{m_0} + 8 \cdot \mathbf{m_1} + 3 \cdot \mathbf{m_2} = \Phi_{\mathcal{B}}^{-1}\left(\begin{pmatrix} -2 \\ 8 \\ 3 \end{pmatrix}\right)$$
coordinate vector

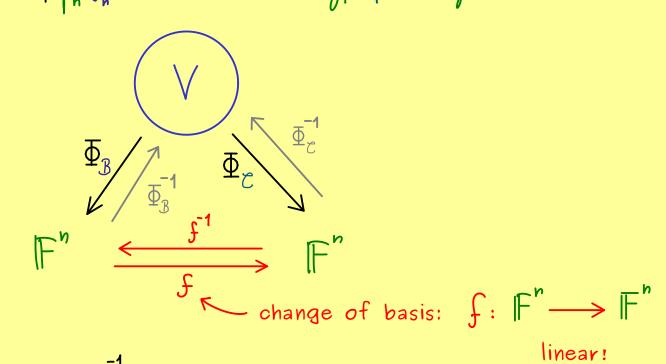
Another basis: 
$$C = (C_1, C_2, C_3)$$
 with  $C_1 = m_0$ ,  $C_2 = m_1$ ,  $C_3$  polynomial 
$$P = \Phi_C^{-1} \begin{pmatrix} -2 \\ 0 \\ 1 \end{pmatrix}$$
 coordinate vector

<u>Old vs. new coordinates</u>:  $B = (b_1, b_2, ..., b_n)$  basis,  $C = (C_1, C_2, ..., C_n)$  basis

$$\Phi_{\mathcal{B}}(v) = \begin{pmatrix} \beta_1 \\ \beta_2 \\ \vdots \\ \beta_n \end{pmatrix} \longleftrightarrow \Phi_{\mathcal{C}}(v) = \begin{pmatrix} \gamma_1 \\ \gamma_2 \\ \vdots \\ \gamma_n \end{pmatrix}$$

$$V = \beta_1 \cdot b_1 + \dots + \beta_n \cdot b_n$$

$$V = \gamma_1 \cdot C_1 + \dots + \gamma_n \cdot C_n$$



We get:  $f(x) = \Phi_{\mathcal{C}} \circ \Phi_{\mathcal{B}}^{-1}(x)$